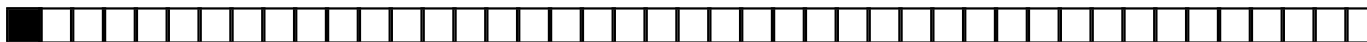


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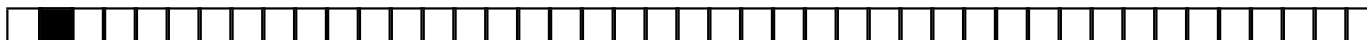
Optimal Testing in Functional Analysis of
Variance Models

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PLAN

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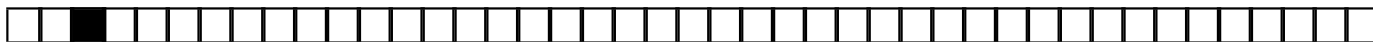
■ INTRODUCTION

■ *Analysis of variance* (ANOVA) - one of the most widely used tools in applied statistics. Useful for handling low dimensional data, limitations in analyzing *functional* responses.

Functional analysis of variance (FANOVA) methods provide alternatives to classical ANOVA methods while still allowing a simple interpretation.

■ General: Ramsay & Silverman (1997, 2002) and Stone *et al.* (1997).

■ Fitting and Estimation of Components: Wahba *et al.*, 1995; Stone *et al.*, 1997; Huang, 1998; Lin, 2000; Gu, 2002.



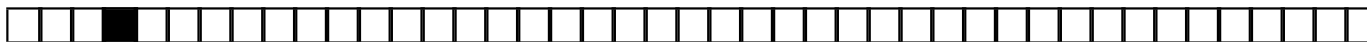
■ MODEL

■ Diffusion version of FANOVA. One observes a series of sample paths of a stochastic process driven by

$$dY_i(\mathbf{t}) = m_i(\mathbf{t}) d\mathbf{t} + \epsilon dW_i(\mathbf{t}), \quad i = 1, \dots, r; \quad \mathbf{t} \in [0, 1]^d,$$

where $\epsilon > 0$ is the diffusion coefficient, r and d are finite integers, m_i are (unknown) d -dimensional response functions and W_i are independent d -dimensional standard Wiener processes.

■ Results of Brown & Low (1996): Under general conditions, the corresponding discrete model is asymptotically equivalent to the diffusion model with $\epsilon = \sigma/\sqrt{n}$.

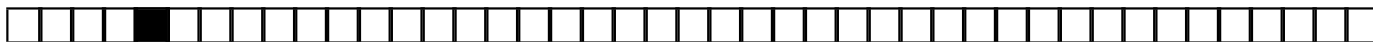


■ MODEL

[Antoniadis, 1984]: Each of the r response functions in model admits the following unique decomposition

$$m_i(\mathbf{t}) = m_0 + \mu(\mathbf{t}) + a_i + \gamma_i(\mathbf{t}) \quad i = 1, \dots, r; \quad \mathbf{t} \in [0, 1]^d,$$

where m_0 is a constant function (the *grand mean*), $\mu(\mathbf{t})$ is either zero or a non-constant function of \mathbf{t} (the *main effect* of \mathbf{t}), a_i is either zero or a non-constant function of i (the *main effect* of i) and $\gamma_i(\mathbf{t})$ is either zero or a non-zero function which cannot be decomposed as a sum of a function of i and a function of \mathbf{t} (the *interaction* component).



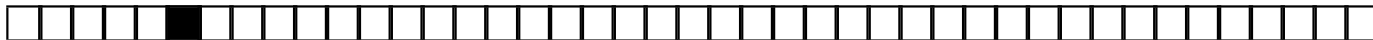
■ IDENTIFIABILITY CONSTRAINTS



$$\int_{[0,1]^d} \mu(\mathbf{t}) \, d\mathbf{t} = 0, \quad \sum_{i=1}^r a_i = 0,$$



$$\sum_{i=1}^r \gamma_i(\mathbf{t}) = 0, \quad \int_{[0,1]^d} \gamma_i(\mathbf{t}) \, d\mathbf{t} = 0, \quad \forall i = 1, \dots, r; \quad \mathbf{t} \in [0, 1]^d.$$



■ Difficulties of Pointwise ANOVA

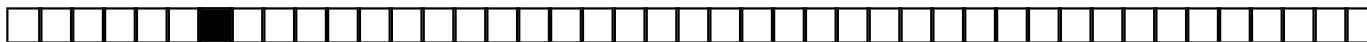
■ “Dissipation of power.”

■ Fan & Lin (1998) proposed a powerful overall test for functional hypothesis testing → decomposition of the original functional data into Fourier (or wavelet) series expansions + adaptive Neyman and wavelet thresholding procedures of Fan (1996) to the resulting empirical Fourier (wavelet) coefficients.

Idea: *Sparsity* of data in non-standard (wavelet) domains.

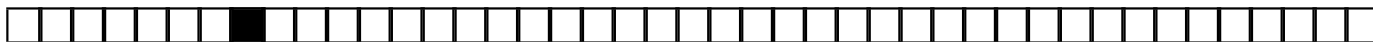
■ Similar in Eubank (2000) and Dette & Derbort (2001).

■ Guo (2002) suggested a MLR based test for functional variance components in mixed-effects FANOVA models.



■ Optimality of Tests?

- Not discussed in FANOVA context.
- We derive asymptotically (as $\epsilon \rightarrow 0$ or, equivalently, as $n \rightarrow \infty$) optimal (minimax) *non-adaptive* and *adaptive* testing procedures for testing the significance of the main effect and the interactions in the FANOVA model against composite nonparametric alternatives (separated away from null in $L^2([0, 1]^d)$ -norm)
- Gaussian **signal + noise** models: Ingster (1982, 1993), Ermakov (1990), Spokoiny (1996, 1998), Lepski & Spokoiny (1999), Ingster & Suslina (2000) and Horowitz & Spokoiny (2001)



■ Hypotheses to be Tested 1

Testing the significance of the main effects and the interactions

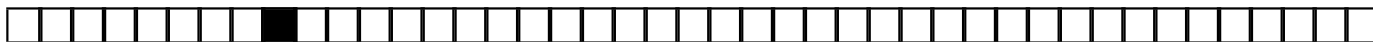
$$H_0 : \mu(\mathbf{t}) \equiv 0, \quad \mathbf{t} \in [0, 1]^d,$$

$$H_0 : \gamma_i(\mathbf{t}) \equiv 0, \quad \forall i = 1, \dots, r, \quad \mathbf{t} \in [0, 1]^d.$$

Identifiability constraints \rightarrow

$$Y_i^* = m_0 + a_i + \epsilon \xi_i, \quad i = 1, \dots, r, \quad \sum_{i=1}^r a_i = 0,$$

where $Y_i^* = \int_{[0,1]^d} dY_i(\mathbf{t})$ and ξ_i are independent $\mathcal{N}(0, 1)$ random variables. This is the classical one-way fixed-effects ANOVA model.



■ Hypotheses to be Tested 2

We assume that m_i (and, hence, μ and γ_i as well) belong to a Besov ball of radius $C > 0$ on $[0, 1]^d$, $B_{p,q}^s(C)$, where $s > 0$ and $1 \leq p, q \leq \infty$.

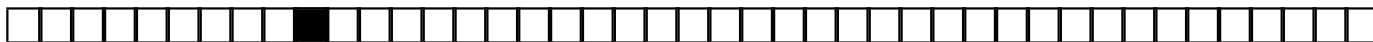
■ Interested in: **Rate** at which the distance between the null and alternative hypotheses decreases to zero, while still permitting consistent testing. Alternatives are separated away from the null by ρ in the $L^2([0, 1]^d)$.

■ Alternatives are of the form

$$H_1 : \mu \in \mathcal{F}(\rho),$$

$$H_1 : \gamma_i \in \mathcal{F}(\rho), \quad \text{at least for one } i = 1, \dots, r,$$

where $\mathcal{F}(\rho) = \{f \in B_{p,q}^s(C) : \|f\|_2 \geq \rho\}$.



■ Minimax Optimality 1

Consider the general model

$$dZ(\mathbf{t}) = f(\mathbf{t}) d\mathbf{t} + \epsilon dW(\mathbf{t}), \quad \mathbf{t} \in [0, 1]^d,$$

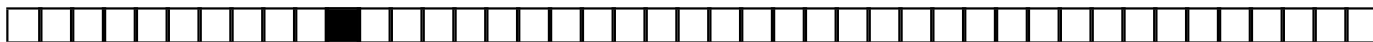
where W is a d -dimensional standard Wiener process.

We wish to test

$$H_0 : f \equiv 0 \quad \text{versus} \quad H_1 : f \in \mathcal{F}(\rho),$$

where $\mathcal{F}(\rho) = \{f \in B_{p,q}^s(C) : \|f\|_2 \geq \rho\}$.

■ For prescribed α and β , the rate of decay to zero of the “indifference threshold” $\rho = \rho(\epsilon)$, as $\epsilon \rightarrow 0$, can be viewed as a **measure of goodness of a test**. It is natural to seek the test with the optimal (fastest) rate.



■ Minimax Optimality 2

[Ingster, 1993; Spokoiny, 1996; Ingster & Suslina, 2000].

Definition $\rho(\epsilon)$ is the minimax rate of testing if $\rho(\epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$ and the following two conditions hold

(i) for any $\rho'(\epsilon)$ satisfying $\rho'(\epsilon)/\rho(\epsilon) = o_\epsilon(1)$, one has

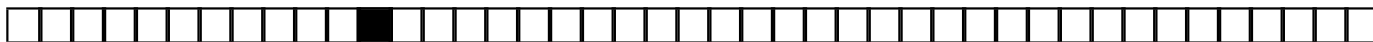
$$\inf_{\phi_\epsilon} [\alpha(\phi_\epsilon) + \beta(\phi_\epsilon, \rho'(\epsilon))] = 1 - o_\epsilon(1),$$

where $o_\epsilon(1) \rightarrow 0$ as $\epsilon \rightarrow 0$.

(ii) for any $\alpha > 0$ and $\beta > 0$ there exists a constant $c > 0$ and a test ϕ_ϵ^* such that

$$\alpha(\phi_\epsilon^*) \leq \alpha + o_\epsilon(1), \quad \beta(\phi_\epsilon^*, c\rho(\epsilon)) \leq \beta + o_\epsilon(1).$$

ϕ_ϵ^* is called an asymptotically optimal (minimax) test.



■ Minimax Optimality 3

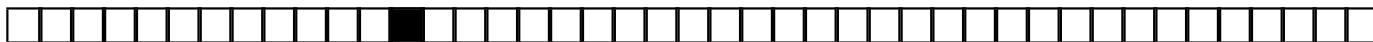
■ Ingster (1993) and Lepski & Spokoiny (1999) showed that for $sp > d$ the asymptotically optimal (minimax) rate is

$$\rho(\epsilon) = \epsilon^{4s''/(4s''+d)},$$

where $s'' = \min(s, s - \frac{d}{2p} + \frac{d}{4})$.

■ The proposed asymptotically optimal (minimax) tests were consistent but *non-adaptive* [involve the smoothness parameters s and p of the corresponding Besov ball].

■ Spokoiny (1996) and Horowitz & Spokoiny (2001): Problem of *adaptive* minimax testing where s and p are unknown. **No adaptive test can achieve the exact optimal rate uniformly over all s and p** (in some given range).

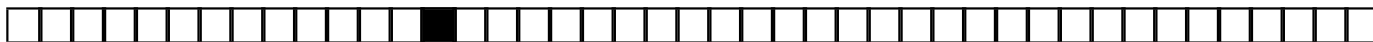


■ Minimax Optimality 4

■ Price for Adaptivity: If one allows increase of $\rho(\epsilon)$ by an additional log-log factor $t_\epsilon = (\ln \ln \epsilon^{-2})^{1/4}$, i.e, considers $\rho(\epsilon t_\epsilon)$ instead of $\rho(\epsilon)$, then [Horowitz & Spokoiny (2001)] the optimal rate of adaptive testing is

$$\rho(\epsilon t_\epsilon) = (\epsilon t_\epsilon)^{4s''/(4s''+d)},$$

■ The “price” factor t_ϵ is unavoidable and cannot be reduced.



■ Wavelet Bases

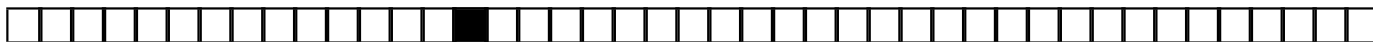
We assume $d = 1$ and work with periodic o.n. wavelet bases in $L^2([0, 1])$ generated by shifts of a compactly supported scaling function ϕ , i.e.

$$\phi^{\text{P}}(t) = \sum_{\ell \in \mathbb{Z}} \phi(t - \ell), \quad \psi_{jk}^{\text{P}}(t) = \sum_{\ell \in \mathbb{Z}} \psi_{jk}(t - \ell), \quad j \geq 0, k = 0, \dots, 2^j - 1$$

where

$\psi_{jk}(t) = 2^{j/2} \psi(2^j t - k)$. $\{\phi^{\text{P}}; \psi_{jk}^{\text{P}}, j \geq 0, k = 0, 1, \dots, 2^j - 1\}$ generates an o.n. basis in $L^2([0, 1])$.

If the MRA is of regularity $r > 0$, the corresponding wavelet basis is **unconditional** for Besov spaces $B_{p,q}^s([0, 1])$ for $0 < s < r$, $1 \leq p, q \leq \infty$. Such bases characterize Besov balls in terms of wavelet coefficients.



■ Testing in FANOVA 1

Averaging over r paths + identifiability conditions:

$$d\bar{Y}(t) = (m_0 + \mu(t)) dt + \epsilon d\bar{W}(t), \quad t \in [0, 1]$$

$$d(Y_i - \bar{Y})(t) = (a_i + \gamma_i(t)) dt + \epsilon d(W_i - \bar{W})(t), \quad i = 1, \dots, r.$$

$\{W_i - \bar{W}; i = 1, \dots, r\}$ are Wiener processes with the same covariance kernel $C(s, t) = \frac{r-1}{r} \min(s, t)$ [but no independent].

$$dZ(t) = f(t) dt + \eta dW(t), \quad t \in [0, 1],$$

■ $Z(t) = \bar{Y}(t), f(t) = m_0 + \mu(t), \eta = \epsilon/\sqrt{r}$

■ $Z(t) = (Y_i - \bar{Y})(t), f(t) = a_i + \gamma_i(t), \eta = \epsilon\sqrt{(r-1)/r}$



■ Testing in FANOVA 2

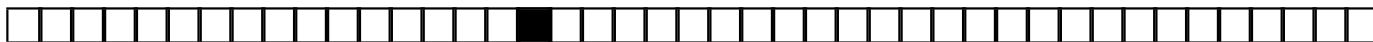
To apply Spokoiny (1996) results, assume that $B_{p,q}^s(C)$ satisfies $1 \leq p, q \leq \infty$, $sp > 1$ and $s - \frac{1}{2p} + \frac{1}{4} > 0$. [Donoho *et al.*, 1995; Donoho & Johnstone, 1998)].

$$H_0 : f \equiv \text{constant} \left(= \int_0^1 f(t) dt \right)$$

versus

$$H_1 : \left(f - \int_0^1 f(t) dt \right) \in \mathcal{F}(\rho),$$

where $\mathcal{F}(\rho) = \{f \in B_{p,q}^s(C) : \|f\|_2 \geq \rho\}$, $1 \leq p, q \leq \infty$, $sp > 1$ and $s - \frac{1}{2p} + \frac{1}{4} > 0$.



■ Testing in FANOVA 3

■ Choose a wavelet ψ of regularity $r > s$. One has

$$Y_{jk} = \theta_{jk} + \eta \xi_{jk}, \quad j \geq -1; \quad k = 0, 1, \dots, 2^j - 1,$$

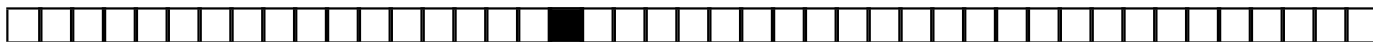
where $Y_{jk} = \int_0^1 \psi_{jk}(t) dZ(t)$, $\theta_{jk} = \int_0^1 \psi_{jk}(t) f(t) dt$ and ξ_{jk} are independent $\mathcal{N}(0, 1)$ random variables.

■ Testing

$$H_0 : f \equiv \text{constant}$$

is equivalent to testing

$$H_0 : \theta_{jk} = 0 \quad \forall j \geq 0; \quad k = 0, 1, \dots, 2^j - 1.$$



■ NON-ADAPTIVE TEST 1

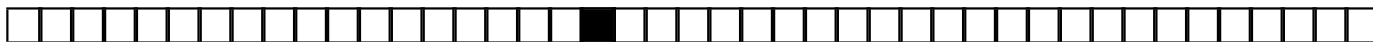
RESULT Let the MRA be of regularity $r > s$, and let the parameters s, p, q and the radius C of the Besov ball $B_{p,q}^s(C)$ be **known**, where $1 \leq p, q \leq \infty$, $sp > 1$, $s - \frac{1}{2p} + \frac{1}{4} > 0$ and $C > 0$. Then, for a fixed significance level $\alpha \in (0, 1)$, the test ϕ^* , for testing

$$H_0 : f \equiv \text{constant} \quad \text{vs} \quad H_1 : \left(f - \int_0^1 f(t) dt \right) \in \mathcal{F}(\rho),$$

where $\mathcal{F}(\rho) = \{f \in B_{p,q}^s(C) : \|f\|_2 \geq \rho\}$, is α -level asymptotically optimal (minimax) test, as $\eta \rightarrow 0$. That is, for any $\beta \in (0, 1)$, it attains the optimal rate of testing

$$\rho(\eta) = \eta^{4s''/(4s''+1)},$$

where $s'' = \min\{s, s - \frac{1}{2p} + \frac{1}{4}\}$.



■ NON-ADAPTIVE TEST 2

■ ϕ^* is based on the sum of squares of the thresholded empirical wavelet coefficients Y_{jk} with properly chosen level-dependent thresholds. The null hypothesis is rejected when this sum of squares exceeds some critical value.

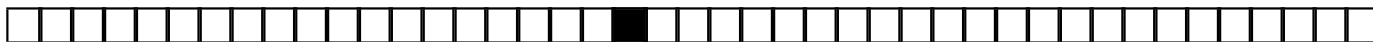
■ j_η the largest integer: $j_\eta \leq \log_2 \eta^{-2}$.

■ $j(s)$ resolution level given by

$$j(s) = \frac{2}{4s'' + 1} \log_2 (C\eta^{-2}).$$

■ Levels split as:

$$\mathcal{J}_- = \{0, \dots, j(s) - 1\}, \quad \mathcal{J}_+ = \{j(s), \dots, j_\eta - 1\}.$$



■ NON-ADAPTIVE TEST 3

■ For each $j \in \mathcal{J}_-$, define

$$S_j = \sum_{k=0}^{2^j-1} (Y_{jk}^2 - \eta^2)$$

■ For each $j \in \mathcal{J}_+$ and for given threshold $\lambda > 0$, define

$$S_j(\lambda) = \sum_{k=0}^{2^j-1} [(Y_{jk}^2 \mathbf{1}(|Y_{jk}| > \eta\lambda) - \eta^2 b(\lambda)],$$

where $b(\lambda) = \mathbb{E} [\xi^2 \mathbf{1}(|\xi| > \lambda)]$ and $\xi \sim \mathcal{N}(0, 1)$.



■ NONADAPTIVE TEST 4

■ Define

$$T(j(s)) = \sum_{j=0}^{j(s)-1} S_j,$$

and

$$Q(j(s)) = \sum_{j=j(s)}^{j_\eta-1} S_j(\lambda_j),$$

where $\lambda_j = 4\sqrt{(j - j(s) + 8) \ln 2}$.

■ Under H_0 ,

$v_0^2(j(s)) = 2\eta^4 2^{j(s)}$ and $w_0^2(j(s)) = \eta^4 \sum_{j=j(s)}^{j_\eta-1} 2^j d(\lambda_j)$, are the variances of $T(j(s))$ and $Q(j(s))$, respectively, where $d(\lambda_j) = \mathbb{E} [\xi^4 \mathbf{1}(|\xi| > \lambda_j)]$.



■ NON-ADAPTIVE TEST 5

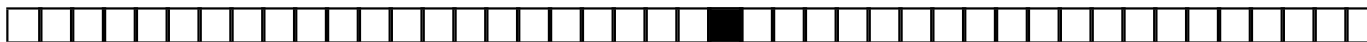
Comment: In MATLAB simulations we replaced the expression from Fan (1996):

$$\begin{aligned} \mathbb{E}(\xi^{2k} \mathbf{1}(|\xi| > \lambda_j)) &= \sqrt{2/\pi} \lambda_j^{2k-1} 2^{-8(j-j(s)+8)} \\ &+ O\left(\lambda_j^{2k-3} 2^{-8(j-j(s)+8)}\right), \quad k = 1, 2, \dots \end{aligned}$$

by

$$d(\lambda_j) = 3 - \sqrt{2/\pi} \Lambda_j^5 / 5 + \Lambda_j^7 / (7\sqrt{2\pi}) + o(\Lambda_j^8),$$

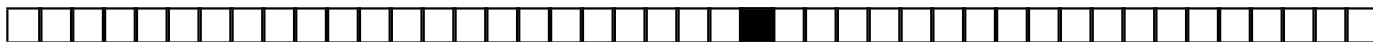
where $\Lambda_j = \min(\lambda_j, 1/\lambda_j)$. Similar approximation can be derived for $b(\lambda_j) = \mathbb{E}(\xi^2 \mathbf{1}(|\xi| > \lambda_j))$.



■ NON-ADAPTIVE TEST 6

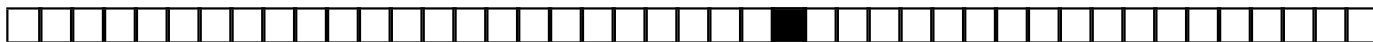
■ Finally, for a given significance level $\alpha \in (0, 1)$, let ϕ^* be the test defined by

$$\phi^* = \begin{cases} \mathbf{1} \{T(j(s)) > v_0(j(s))z_{1-\alpha}\}, & \text{if } p \geq 2 \\ \mathbf{1} \left\{ T(j(s)) + Q(j(s)) > \sqrt{v_0^2(j(s)) + w_0^2(j(s))} z_{1-\alpha} \right\}, \\ \quad \text{if } 1 \leq p < 2, \end{cases}$$



■ ADAPTIVE TEST 1

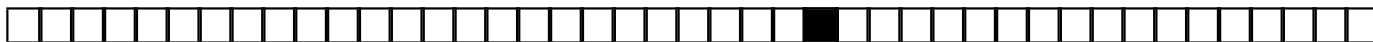
- The parameters s, p, q and the radius C of the corresponding Besov ball $B_{p,q}^s(C)$ are unknown. Assume that $0 < s \leq s_{\max}, 1 \leq p, q \leq \infty, sp > 1, s - \frac{1}{2p} + \frac{1}{4} > 0$ and $0 < C \leq C_{\max}$.
- Let $t_\eta = (\ln \ln \eta^{-2})^{1/4}$ and $j_{\min} = \frac{2}{4s_{\max}+1} \log_2 \eta^{-2}$.
- Regularity of MRA: $r > s_{\max}$.
- The idea: Consider the range of $j(s) = j_{\min}, \dots, j_\eta - 1$ and reject H_0 if it is rejected at least for one selected level $j(s)$.



■ ADAPTIVE TEST 2

Since $\text{card}(\{j_{\min}, \dots, j_{\eta} - 1\}) = O(\ln \eta^{-2})$, Bonferroni type testing leads to the asymptotically *adaptive* test

$$\phi_{\eta}^* = \mathbf{1} \left[\max_{j_{\min} \leq j(s) \leq j_{\eta} - 1} \left\{ \frac{T(j(s)) + Q(j(s))}{\sqrt{v_0^2(j(s)) + w_0^2(j(s))}} \right\} > \sqrt{2 \ln \ln \eta^{-2}} \right].$$



■ ADAPTIVE TEST 3

Spokoiny (1996) showed that the test ϕ_η^* is an adaptive optimal test, i.e.

$$\alpha(\phi_\eta^*) = o_\eta(1)$$

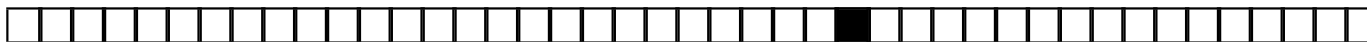
and

$$\sup_{\mathcal{T}} \beta(\phi_\eta^*, c\rho(\eta t_\eta)) = o_\eta(1),$$

where $\rho(\eta t_\eta) = (\eta t_\eta)^{4s''/(4s''+1)}$, $o_\eta(1) \rightarrow 0$ as $\eta \rightarrow 0$, and c is a constant.

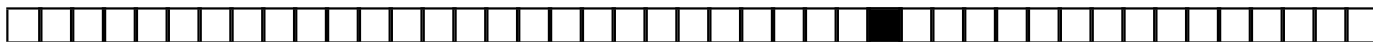
If it is known that $p \geq 2$ then the adaptive test can be simplified to

$$\phi_\eta^* = \mathbf{1} \left[\max_{j_{\min} \leq j(s) \leq j_\eta - 1} \left\{ \frac{T(j(s))}{\sqrt{v_0^2(j(s))}} \right\} > \sqrt{2 \ln \ln \eta^{-2}} \right].$$



■ A COMMENT

The test ϕ_η^* is similar in spirit to that in Fan (1996) and Fan & Lin (2000), though they apply a *global* threshold.



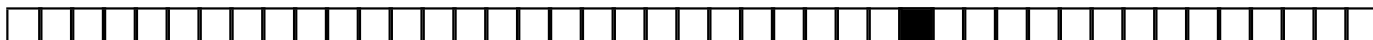
■ APPLICATIONS

■ SIMULATION STUDY 1

■ Synthetic data from the battery of standard test functions of Donoho & Johnstone (1995): BLOCKS, BUMPS, DOPPLER and HEAVISINE. Additional test function MISHMASH, defined as

$$\text{MISHMASH} = -(\text{BLOCKS} + \text{BUMPS} + \text{DOPPLER} + \text{HEAVISINE}),$$

added because of the identifiability constraints.



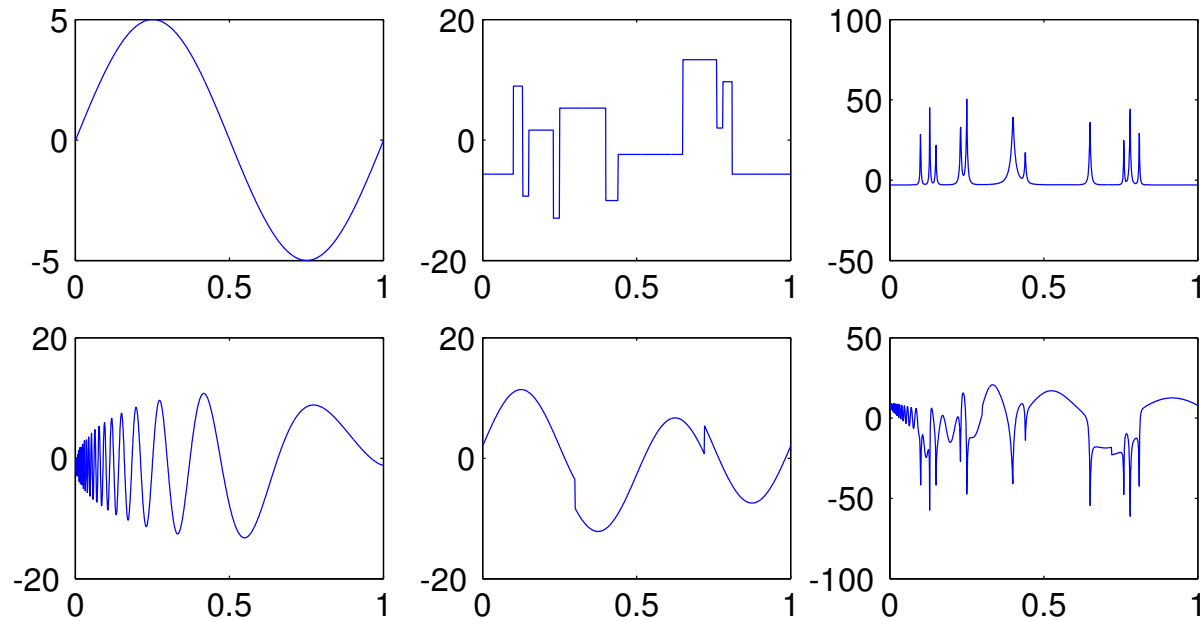
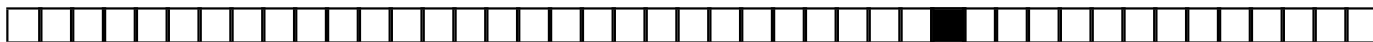
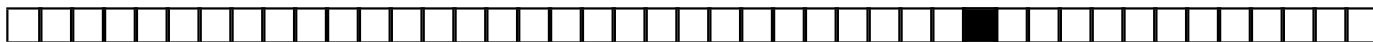


Figure 1: The mean function $\mu(t) = 5 \sin(2\pi t)$ and the centered treatment effect functions $\gamma_i(t)$, $i = 1, \dots, 5$ (i.e., centered BLOCKS, BUMPS, DOPPLER, HEAVISINE, and MISHMASH), sampled at $n = 1024$ data points.



■ SIMULATION STUDY 3

- $m_0 = 1, \mu(t) = 5 \sin(2\pi t)$
- Five simulated observations (one for each test function shown; length ($n = 1024$), two SNRs (SNR = 3 and 7).



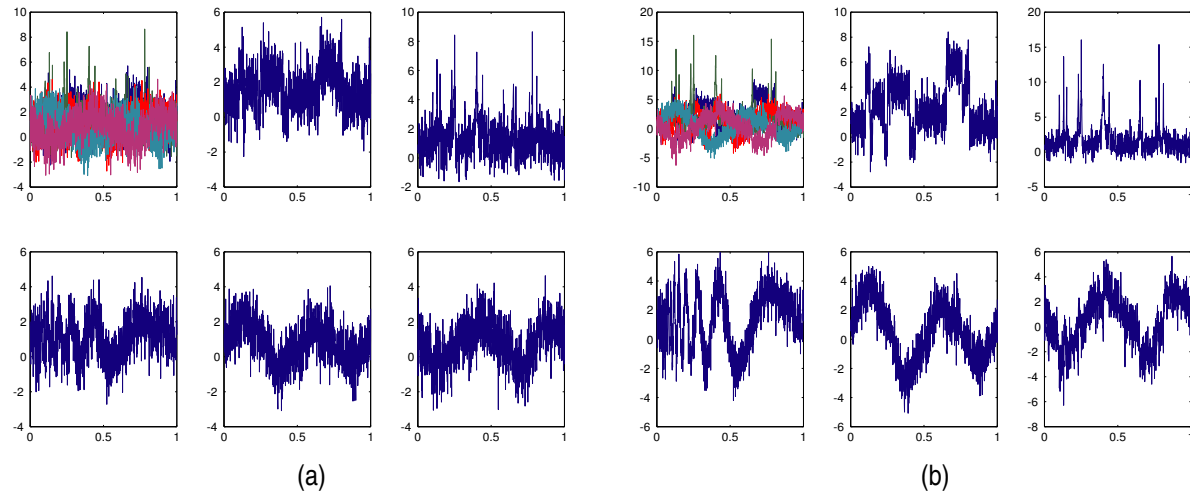
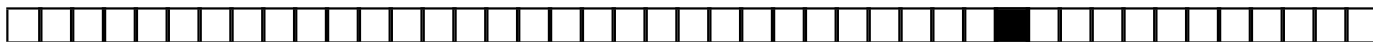


Figure 2: Five simulated observations (one for each test function shown in Figure 1) sampled at $n = 1024$ data points are shown superimposed (first plot) and separately (remaining five plots) for (a) $\text{SNR} = 3$ and (b) $\text{SNR} = 7$.



■ SIMULATION STUDY 4

■ To test the hypothesis $H_0 : \mu(t) = 0$, nonadaptive test,
 $p \geq 2$. ■ Symmlet 8-tap

■ $j(s) = 3$

■ SNR=3: $T(3) = 15.28$ critical value 1.5949

■ SNR=7: $T(3) = 97.52$ critical value 1.6316.

■ $H_0 : \gamma_i(t) = 0$ ($i = 1, \dots, 5$), non-adaptive test, $1 \leq p < 2$. ■
 Daubechies 6-tap

■ $j(s) = 3$ ■ $j_\eta = 7$.

■ SNR=3, $T(3) + Q(3) = 275.3326$ critical value 154.6294

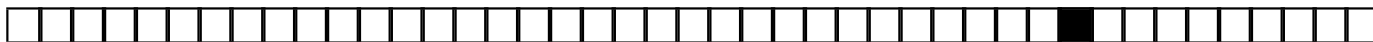
■ SNR=7, $T(3) + Q(3) = 5941.099$ critical value 156.4943



■ SIMULATION STUDY 5

■ Extensive power analysis for the above tests against the composite alternatives

$$H_1 : \mu \in \mathcal{F}(\rho) \quad \text{and} \quad H_1 : \frac{1}{5} \sum_{i=1}^5 \gamma_i \in \mathcal{F}(\rho). \quad (1)$$



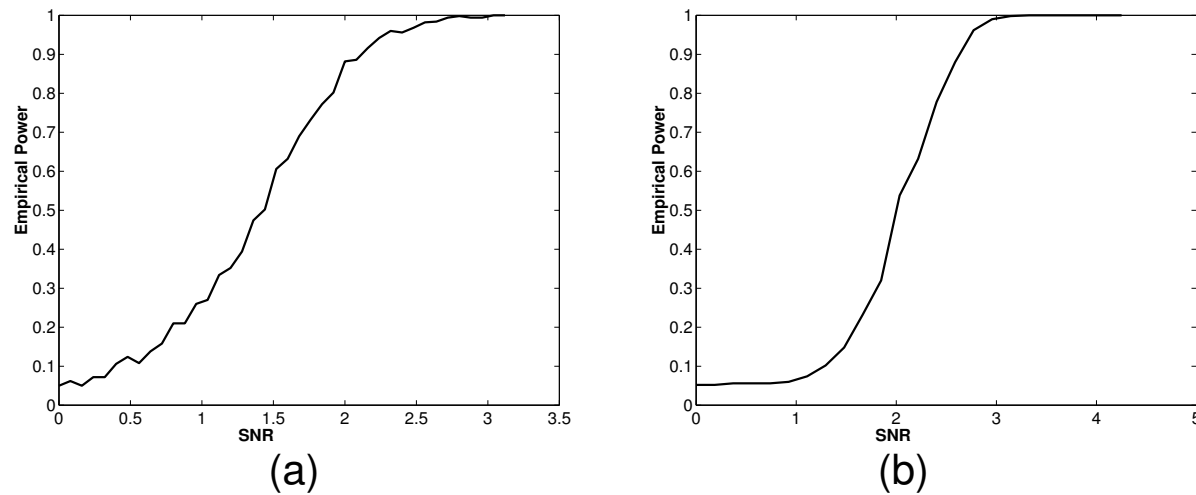
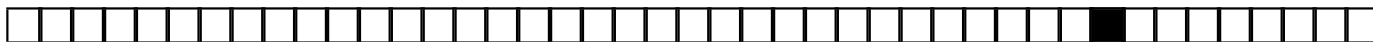
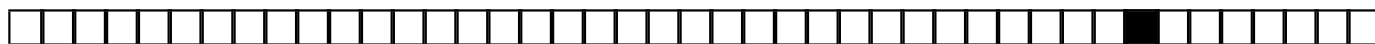


Figure 3: Empirical power functions for testing (a) $H_0 : \mu(t) = 0$ versus $H_1 : \|\mu\|_2 = \rho$ and (b) $H_0 : \gamma_i(t) = 0$ ($i = 1, \dots, 5$) versus $H_1 : \|\sum_i \gamma_i/5\|_2 = \rho$. In both panels, the sample size was $n = 512$ and the number of trials at a fixed discretized SNR was 500.



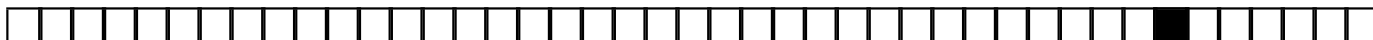
■ ORTHOSIS DATA ANALYSIS 1

- Interesting data on human movement.
- Data: Amarantini David and Martin Luc, Laboratoire Sport et Performance Motrice, Grenoble University
- Underlying movement under various levels of an externally applied force to the knee.
- Seven young male volunteers wore a spring-loaded orthosis of adjustable stiffness under 4 experimental conditions:
 - Control condition (without orthosis),
 - Orthosis condition,
 - Two conditions (Spring1, Spring2) stepping in place was perturbed by fitting a spring-loaded orthosis onto the right knee.



■ ORTHOSIS DATA ANALYSIS 2

■ The data set consists in 280 separate runs and involves the seven subjects over four described experimental conditions, replicated ten times for each subject.



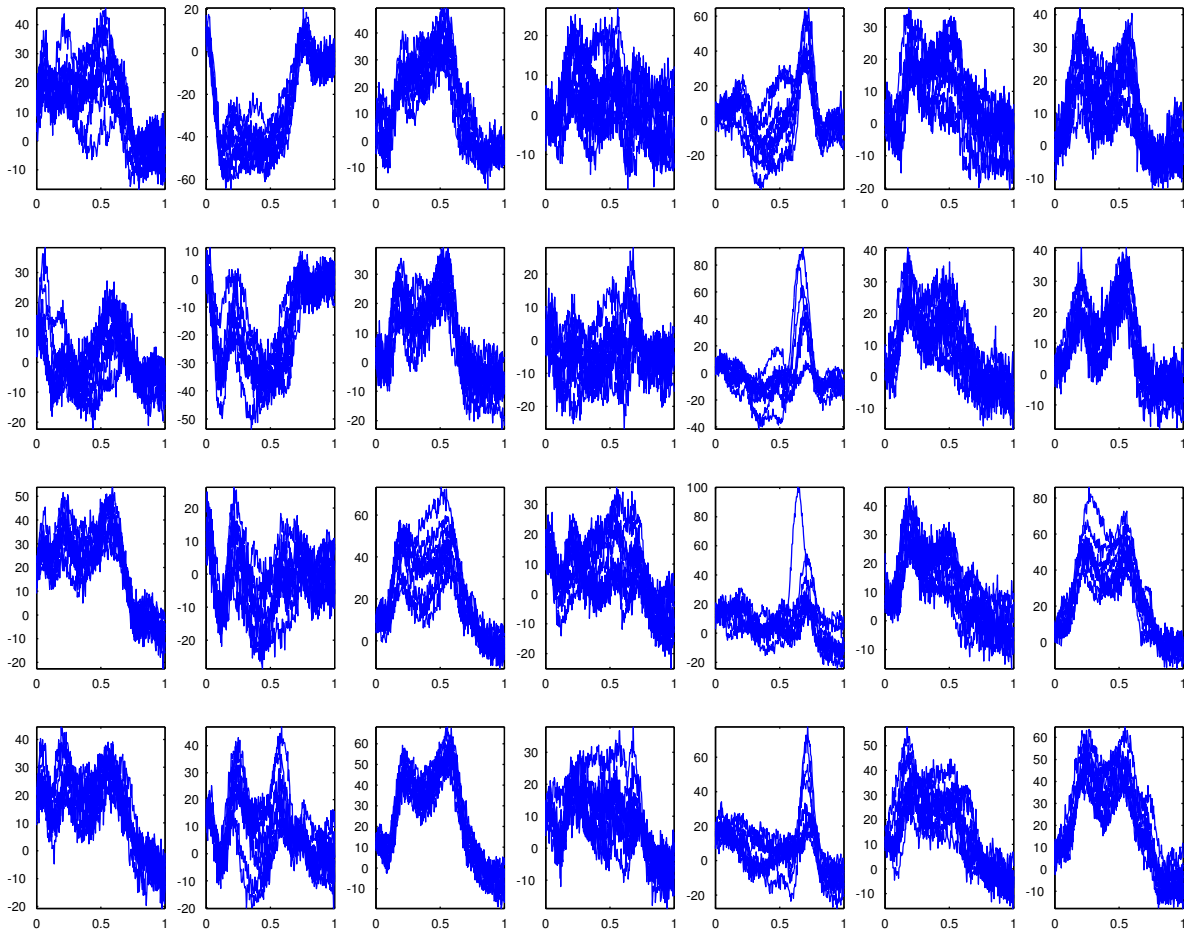


Figure 4: Orthosis data set: panels in rows correspond to *Treatments* while the panels in columns correspond to *Subjects*.



■ ORTHOSIS DATA ANALYSIS 3: MODEL

■ Model

$$dY_{ijk}(t) = m_{ij}(t) dt + \epsilon dW_{ijk}(t),$$

$$i = 1, \dots, I; j = 1, \dots, J; k = 1, \dots, K; t \in [0, 1],$$

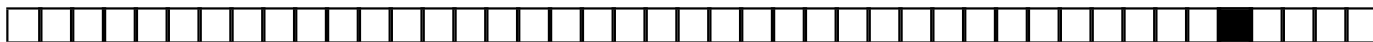
with

$$m_{ij}(t) = m_0 + \mu(t) + \alpha_i + \gamma_i(t) + \beta_j + \delta_j(t),$$

$$i = 1, \dots, I; j = 1, \dots, J; t \in [0, 1],$$

where i is the condition index, j is the subject index, k is the replication index, and t is the time.

■ Subjects in the above model are naturally considered as **block effects**; subjects obviously differ but the researchers are not interested in their differences.



■ ORTHOSIS DATA ANALYSIS 4: MODEL

$$d\bar{Y}_{i..}(t) = m_i(t) dt + \eta dW_{i..}(t), \quad i = 1, \dots, I; \quad t \in [0, 1],$$

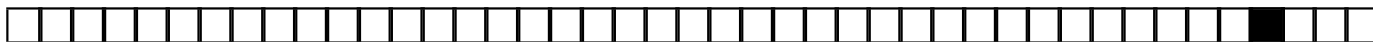
with

$$m_i(t) = m_0 + \mu(t) + \alpha_i + \gamma_i(t), \quad i = 1, \dots, I; \quad t \in [0, 1],$$

where $\eta = \epsilon / \sqrt{JK}$.

■ $j(s) = 4$ and $j_\eta = 6$.

■ *Coiflet 18-tap filter*



■ ORTHOSIS DATA ANALYSIS 5

- Tests $H_0 : \mu(t) = 0$ and $H_0 : \gamma_i = 0$ were both significant.
- The researchers interested contrasts:
 - Control and Orthosis functional treatment effects are equal ($H_0 : \gamma_1(t) = \gamma_2(t)$). Not significant, p -value 0.157
 - Spring 1 and Spring 2 functional treatment effects are equal ($H_0 : \gamma_3(t) = \gamma_4(t)$). Not significant, p -value 0.198.
 - Contrast $(\gamma_1(t) + \gamma_2(t)) - (\gamma_3(t) + \gamma_4(t))$. Significant, p -value is 0.0103.



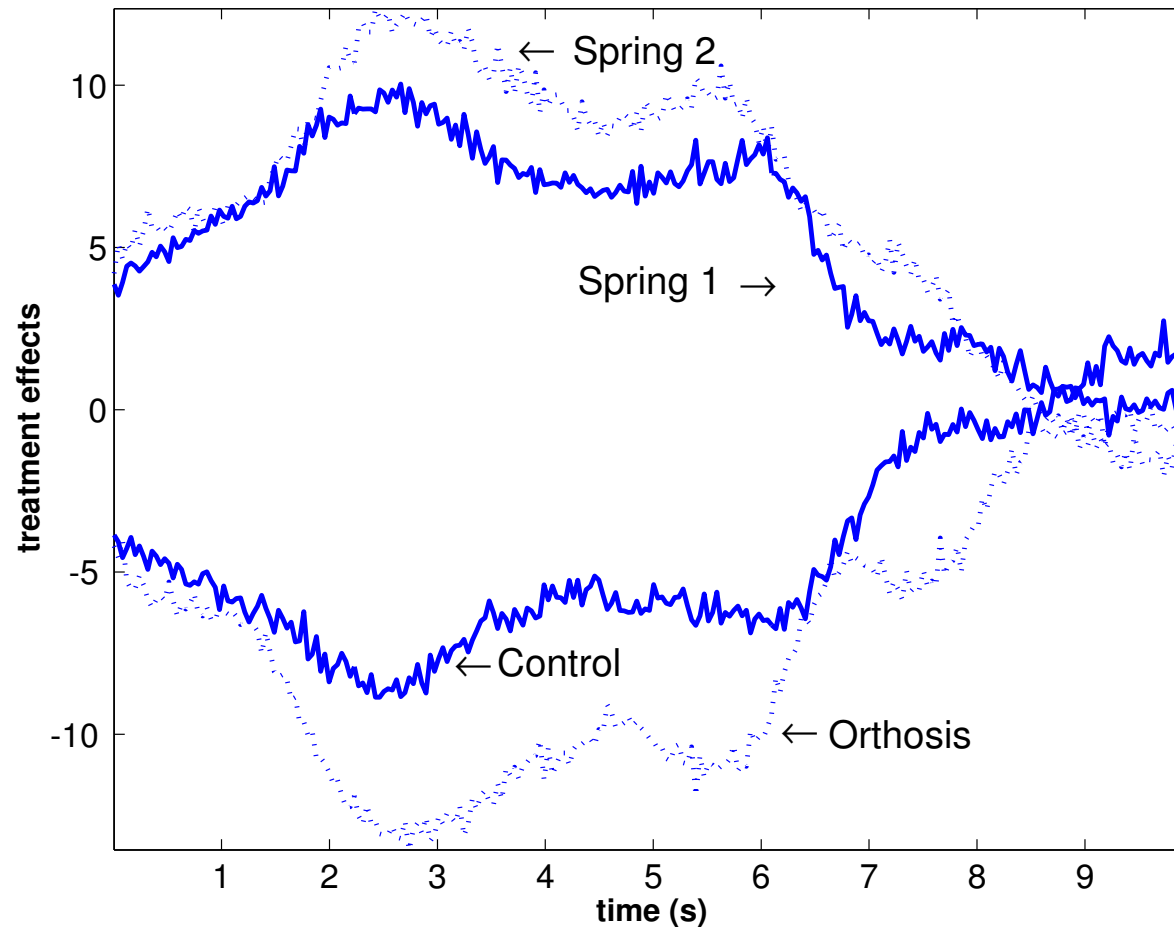


Figure 5: Empirical estimators of the treatment effects of interest. Constant and functional components α_i and $\gamma_i(t)$ ($i = 1, \dots, 4$) are not separated.



■ CONCLUSIONS

- $dY(s, t) = (m_0 + a(s) + \mu(t) + \gamma(s, t)) dt ds + \epsilon dW(s, t), \quad (s, t) \in [0, 1]^2$
- $d \geq 2$, [Thresholding? Block Thresholding, FDR?]
- Black Box Procedure: Variances of T, S by bootstrap [wavestrap, Percival et al. 1999].
- Data, Matlab Files: `brani@isye.gatech.edu`.

