



Towards
Objective
Priors

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Nonparametric
Regression

Illustrations

Summary

Towards Objective Priors in Nonparametric Regression and Classification

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Problem Setting

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Consider the nonparametric regression problem with data $\{Y_i, \mathbf{x}_i\}$ $i = 1, \dots, n$

$$E[Y | \mathbf{x}] = f(\mathbf{x}), \quad \mathbf{x} \in \mathcal{X}$$

Prior Distributions on f :

- ▶ Gaussian Process Priors
- ▶ Dirichlet Process priors
- ▶ Expansions of f (finite and infinite)



Basis Expansions

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Need to place a prior distribution on unknown function $f \in \mathcal{F}$
Expansions $f(\mathbf{x}_i) = \sum_j \psi_j(\mathbf{x}_i) \beta_j$

- ▶ $\{\psi_j\}$: basis functions for some function space \mathcal{F}
- ▶ $\{\beta_j\}$ unknown coefficients
- ▶ Commonly used basis functions:
 - ▶ Polynomials
 - ▶ Fourier
 - ▶ Splines
 - ▶ Wavelets
 - ▶ Kernels



Over-complete Dictionaries (OCD)

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In recent years OCD have received considerable attention

- ▶ Collection $\{\psi_j(\mathbf{x})\}$ “more than a basis”
- ▶ Examples:
 - ▶ “Large p , small n ”
 - ▶ Unions of two (or more) bases
 - ▶ Translation Invariant Wavelets
 - ▶ Free-knot splines
 - ▶ Gabor frames
 - ▶ Kernels: $\psi_j(\mathbf{x}) = k(\mathbf{x}; \omega_j)$ with kernel specific scale & location parameters
- ▶ Expand f in terms of OCD

$$f(\mathbf{x}_i) = \sum_{j \in \mathcal{J}} \psi_j(\mathbf{x}_i) \beta_j, \quad f \in \mathbb{F} = \overline{\{\psi_j\}}$$



Why Over-complete Dictionaries?

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Summary

- + More flexible - local adaptivity
- + Potential for sparse representations
- Non-unique coefficients
- Computationally intensive search over (uncountable) dictionary
- +/- If we are careful, can use improper priors (!) (at least in theory)



Prior Distributions

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Consider finite expansions for some collection of dictionary elements ψ_j

$$f(\mathbf{x}) = \sum_{j \leq J} \psi_j(\mathbf{x}) \beta_j \quad \{\psi_j \in \mathbb{F}\}$$
$$\mathbf{f} = \mathbf{\Psi} \boldsymbol{\beta}$$

Choice of prior distribution on β_j

- ▶ g -priors and mixtures of g priors (Zellner-Siow Cauchy priors)
- ▶ Independent normal or mixtures of normals



Zellner-Siow Cauchy Prior:

$$\beta \mid \Psi \sim \mathbf{N}(0, g\sigma^2(\Psi'\Psi)^{-})$$

$$g \sim \mathbf{G}(1/2, n/2)$$

$$p(\sigma^2) \propto 1/\sigma^2$$

- + Prior on f invariant to choice of basis
- Bayes factors break down if $\text{rank}(\Psi) = n$
(cannot distinguish model from null model)
- Consistent with $\mathbf{f} \sim \mathbf{N}(\mathbf{0}, g\sigma^2\mathbf{I}_n)$



Independent Priors

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Independent normals and scale mixtures of normals used by

- ▶ Silverman & Johnstone (wavelets)
- ▶ Tipping (relevance vector machines)
- ▶ Chakraborty, Ghosh & Mallick (large p , small n nonlinear regression)

$$\begin{aligned}\beta_j \mid \phi_j &\stackrel{ind}{\sim} N(0, \varphi_j^{-1}) \\ \phi_j &\stackrel{iid}{\sim} G(a, b)\end{aligned}$$

Tipping considers modal estimates in the case $a = b = 0$
(improper prior/posterior)

What about the infinite dimensional case $J \rightarrow \infty$?



Lévy Adaptive Regression Kernels (Clyde & Wolpert 2007)

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Representation

$$f(x) = \sum_{j \leq J} k(\mathbf{x}; \omega_j) \beta_j \equiv \int_{\Omega} k(x; \omega) \mathcal{L}(d\omega)$$

Gaussian kernel: $k(\mathbf{x}, \omega_j) = \exp\{-\mathbf{x} - \boldsymbol{\chi}_j\}' \boldsymbol{\Lambda}_j (\mathbf{x} - \boldsymbol{\chi}_j)\}$

\mathcal{L} is a Signed Measure:

$$\mathcal{L}(d\omega) = \sum_{j \leq J} \beta_j \delta_{\omega_j}(d\omega)$$

- ▶ support points of \mathcal{L} : $\{\omega_j\} = \{\boldsymbol{\chi}_j, \boldsymbol{\Lambda}_j\}$
 - ▶ “location” of kernel: $\boldsymbol{\chi}_j \in \mathcal{X}$
 - ▶ “scale” of kernel: $\boldsymbol{\Lambda}_j \in \mathbb{R}^+$
- ▶ jump sizes of measure: β_j
- ▶ number of support points J



Lévy Random Fields

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- ▶ $\mathcal{L}(d\omega)$ is a random (signed) measure on Ω
- ▶ Convenient to think of a random measure as stochastic process where \mathcal{L} assigns random variables to sets $A \in \Omega$
- ▶ Take

$$\mathcal{L} \sim \text{Lv}(\nu) \text{ with Lévy measure } \nu(d\beta, d\omega)$$

where ν satisfies integrability condition:

$$\int_{\mathbb{R} \times \Omega} \min(1, \beta^2) \nu(d\beta, d\omega) < \infty$$

Poisson Representation of Lévy Random Fields is the key to Bayesian Inference!



Poisson Representation

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Goal: $f(x) = \sum_{j < J} k(\mathbf{x}, \omega_j) \beta_j$

Sufficient condition:

$$\int_{\mathbb{R} \times \Omega} \min(1, |\beta|) \nu(d\beta, d\omega) < \infty$$

$$\Rightarrow J \sim P(\nu_+), \quad \nu_+ \equiv \nu(\mathbb{R} \times \Omega)$$

$$\Rightarrow \beta_j, \omega_j \mid J \stackrel{iid}{\sim} \pi(d\beta, d\omega) \propto \nu(d\beta, d\omega).$$

- ▶ Finite number of “big” coefficients $|\beta_j|$
- ▶ Possibly infinite number of $\beta \in [-\epsilon, \epsilon]$
- ▶ Jumps $|\beta_j|$ are absolutely summable¹

¹need to add a term to “compensate” the infinite number of tiny jumps that are not absolutely summable under the more general integrability condition



Lévy Measures

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α -Stable measure: $\nu(d\beta, d\omega) = c_\alpha |\beta|^{-(\alpha+1)} \gamma(d\omega)$

$$\begin{aligned}\beta_j \mid \varphi_j &\stackrel{\text{ind}}{\sim} \text{N}(0, 1/\varphi_j) \\ \varphi_j &\stackrel{\text{iid}}{\sim} \text{G}(\alpha/2, 0)\end{aligned}$$

Notes:

- ▶ Require $0 < \alpha < 2$ for characteristic function for \mathcal{L} and functionals to exist.
- ▶ Cauchy corresponds to $\alpha = 1$
- ▶ Tipping's choice corresponds to $\alpha = 0$
- ▶ Provides a generalization of [Generalized Ridge Priors](#) to infinite dimensional
- ▶ Infinite dimensional analog of Cauchy priors



Approximating Lévy Random Fields

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For α - Stable $\nu^+(\mathbb{R}, \Omega) = \infty$

Truncate measure to obtain a finite expansion:

- ▶ The random number of support points ω with β in $[-\epsilon, \epsilon]^c$ is finite
- ▶ Fix ϵ (practical significance)
- ▶ Use approximate Lévy measure

$$\nu_\epsilon(d\beta, d\omega) \equiv \nu(d\beta, d\omega)\mathbf{1}(|\beta| > \epsilon)\gamma(d\omega)$$

$$\Rightarrow J \sim P(\nu_\epsilon^+) \text{ where } \nu_\epsilon^+ = \nu([-\epsilon, \epsilon]^c, \Omega)$$

$$\Rightarrow \beta_j, \omega_j \stackrel{iid}{\sim} \pi(d\beta, d\omega) \equiv \nu_\epsilon(d\beta, d\omega)/\nu_\epsilon^+$$



Approximate Lévy Prior

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Continuous Approximation:

$$\nu_\epsilon(d\beta, d\omega) = c_\alpha(\beta^2 + \alpha\epsilon^2)^{-(\alpha+1)/2} d\beta \gamma(d\omega)$$

Based on the following hierarchical prior

$$\beta_j \mid \phi_j \stackrel{ind}{\sim} \mathbf{N}(0, \varphi_j^{-1})$$

$$\phi_j \stackrel{ind}{\sim} \mathbf{G}\left(\frac{\alpha}{2}, \frac{\alpha\epsilon^2}{2}\right)$$

$$J \sim \mathbf{P}(\nu_\epsilon^+)$$

where $\nu_{+\epsilon} = \nu_\epsilon(\mathbb{R}, \mathbf{\Omega}) = \frac{\alpha^{1-\alpha/2}\Gamma(\alpha)\Gamma(\alpha/2)}{\epsilon^\alpha\pi^{1/2}\Gamma(\frac{\alpha+1}{2})} \sin(\frac{\pi\alpha}{2})\gamma(\mathbf{\Omega})$

Advantage: Conjugate prior so β can be integrated out for MCMC



Wavelet Test Functions (SNR = 7)

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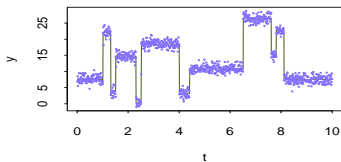
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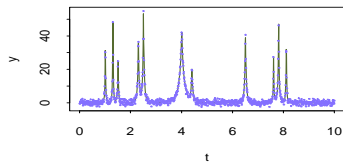
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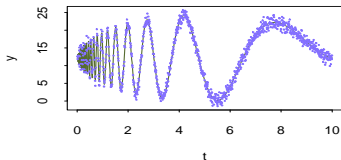
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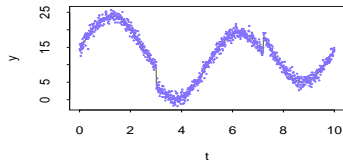
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Kernel Functions

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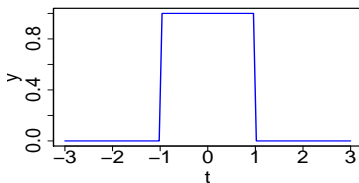
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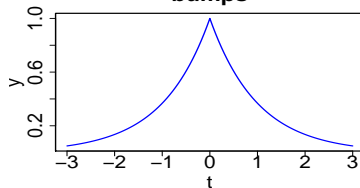
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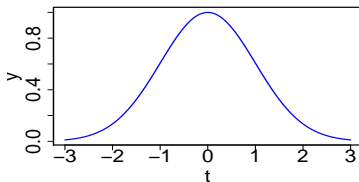
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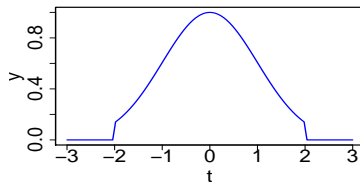
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Comparisons of OCD Methods

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- ▶ Translational Invariant Wavelets – Laplace Priors (Johnstone & Silverman 2005)
- ▶ Continuous Wavelet Dictionary – Compound Poisson with Gaussian Priors (Chu, Clyde, Liang 2007)
- ▶ LARK Symmetric Gamma
- ▶ LARK Cauchy

Range of Over-complete Dictionaries and Priors



Comparison of Mean Square Error w/ OCDs

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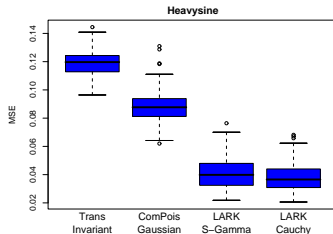
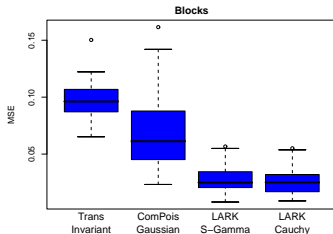
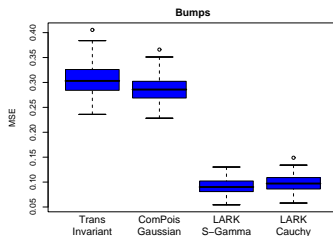
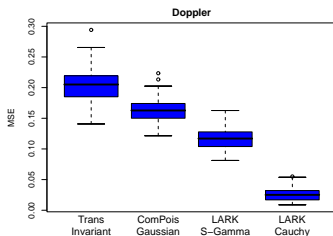
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100 realizations of each function





Higher Dimensional \mathcal{X}

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Summary

MCMC is too slow to allow

- ▶ location χ to be arbitrary; restrict to $\{\mathbf{x}_i\}$
- ▶ scale parameter to vary with location; use common Λ
- ▶ arbitrary Λ ; restrict to diagonal Λ

$$k(\mathbf{x}, \omega_j) = \prod_d \exp\{-\lambda_d(x_d - x_{jd})^2\}$$

$$f(\mathbf{x}) = \sum_j k(\mathbf{x}, \omega_j)\beta_j$$

- ▶ Product structure allows interactions between variables
- ▶ Many input variables may be irrelevant
- ▶ Feature selection; as $\lambda_d \rightarrow 0$ variable x_d is removed



Classification Examples

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Summary

Name	d	data type	n (train/test)
Circle	2	simulation	200/1000
Circle (3 null)	5	simulation	200/1000
Circle (8 null)	10	simulation	200/1000
Circle (18 null)	20	simulation	200/1000
Ionosphere	33	real data	351 (5 cv)
Sonar	60	real data	208 (5 cv)

- ▶ Add latent Gaussian Z_i for probit regression (as in Albert & Chib)
- ▶ Same model as before conditional on \mathbf{Z}
- ▶ Advantage: Draw β in a block from full conditional



Error Rate for Classification

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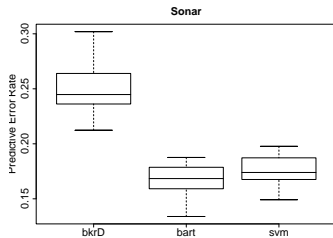
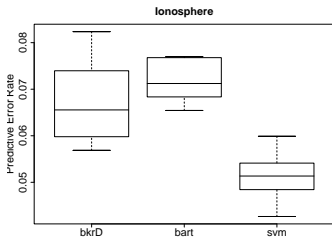
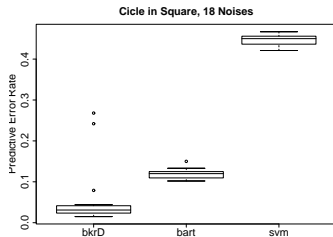
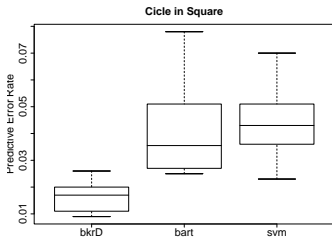
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Feature Selection

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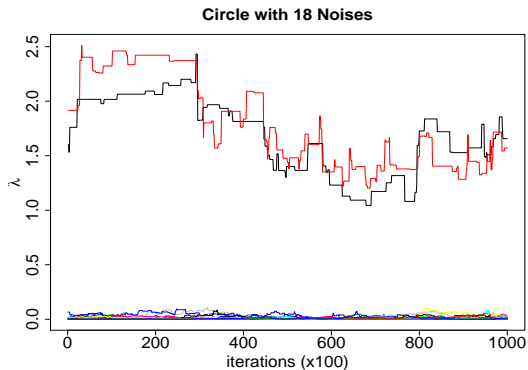
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Trace plots of λ_d for Circle in Square with 18 null predictors





Regression Examples

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Name	d	n (train/test)	Comparison MSE
Friedman 1	10	200/1000	BART < LARK < SVM
Friedman 2	4	200/1000	LARK < BART < SVM
Friedman 3	4	200/1000	BART < LARK < SVM
BostonHousing	13	506 (5 cv)	BART < LARK < SVM
Bodyfat	14	252 (5 cv)	BART < LARK < SVM
Basketball	4	96 (5 cv)	LARK < BART < SVM
Spouse	21	11136/11136	too slow to run



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Lévy Random Field Priors & LARK models:

- ▶ Provide limit of finite dimensional priors (GRP & SVSS) to infinite dimensional setting
- ▶ Proper posterior distribution
- ▶ Allow flexible generating functions (non-parametric)
- ▶ Provide sparse representations compared to SVM & RVM

On going work:

- ▶ Port to C
- ▶ Improve MCMC to allow adaptive λ_{dj} in higher dimensional problems (local interactions & feature selection)